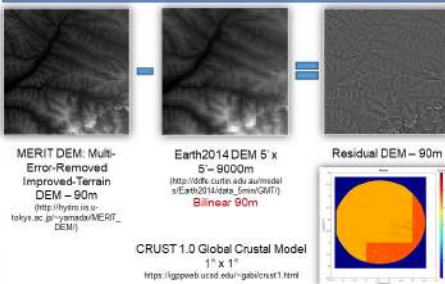


**Introduction**

The definition and realization of the International Height Reference System (IHRIS) were proposed in 2015 based on Resolution No. 1 of the International Association of Geodesy (IAG). Conventionally, the vertical component will be given by the geopotential number. Regardless of the technique adopted to calculate the geopotential value at each station, in order to obtain the high frequency effects of the gravity field, residual terrain modeling (RTM) is a widely used technique (Forsberg, 1984). In the context of spatial domain methods, for the practical solution of Newton's Integral, the topographic continuous masses are discretized using elementary mass bodies for which the gravitational effect can be calculated analytically or numerically. Currently, there are approaches based on the use of point-masses, tesseroids, prisms and polyhedra (Yang, Hirt, Pail, 2020). In terms of strategies for the IHRIS the RTM is an open problem, being recommended the identification of the best configuration, contrasting the results with complementary and independent data (Sanchez et al., 2021). Therefore, this work aimed to analyze the integration of different approaches, with harmonic correction and the use of the CRUST 1.0 global density model to calculate the RTM effect in the future IHRIS PPTE station in Brazil.

**Methodology and numerical tests**



RTM experiment setups				
Integration radius for each approach				
Setup 1	Setup 2	Setup 3	Setup 4	
Polyhedron --	Polyhedron --	Polyhedron --	Polyhedron --	0.02
Prism 1.85	Prism --	Prism --	Prism --	--
Tesseroid --	Tesseroid 1.85	Tesseroid --	Tesseroid --	1.85
Point-mass --	Point-mass --	Point-mass 1.85	Point-mass --	--
Setup 5	Setup 6	Setup 7	Setup 8	
Polyhedron 0.02	Polyhedron 0.03	Polyhedron 0.07	Polyhedron	0.5
Prism --	Prism --	Prism --	Prism --	--
Tesseroid --	Tesseroid --	Tesseroid --	Tesseroid --	--
Point-mass 1.85	Point-mass 1.85	Point-mass 1.85	Point-mass 1.85	1.85

Heck and Seitz (2007)

$$\zeta_{\text{res}}(r, \lambda, \varphi) = G\rho(\lambda, \varphi, \Delta r)\Delta\lambda\Delta\varphi\Delta r \left[ \frac{1}{r_0} + \frac{3(\lambda_0 - \lambda)^2 - \varphi_0^2}{24r_0^2} \Delta\lambda^2 + \frac{3(\lambda_0 - \lambda)^2 - \varphi_0^2}{24r_0^2} \Delta\varphi^2 + \frac{3(\lambda_0 - \lambda)^2 - \varphi_0^2}{24r_0^2} \Delta\lambda\Delta\varphi + O(\Delta^3) \right]$$

$$U_0 = \sqrt{(\lambda_0 - \lambda)^2 + (\varphi_0 - \varphi)^2 + (r_0 - r)^2}$$

$$\zeta_{\text{HC}} = -\frac{4\pi G\rho(\lambda, \varphi, \Delta r)\Delta r^2}{Y}$$

Heck and Seitz (2007)

$$\zeta_{\text{res}}(r, \lambda, \varphi) = G\rho(\lambda, \varphi, \Delta r)\Delta\lambda\Delta\varphi\Delta r \left[ K_{1111} + \frac{1}{24} (K_{1112}\Delta\lambda^2 + K_{1122}\Delta\varphi^2 + K_{1122}\Delta\lambda\Delta\varphi) + O(\Delta^3) \right]$$

$$\lambda_0 = \frac{(\lambda_1 + \lambda_2)}{2}, \varphi_0 = \frac{(\varphi_1 + \varphi_2)}{2}, r_0 = \frac{(r_1 + r_2)}{2}$$

$$\Delta\lambda = \lambda_2 - \lambda_1, \Delta\varphi = \varphi_2 - \varphi_1, \Delta r = r_2 - r_1 = \Delta r_2$$

$$\zeta_{\text{HC}} = -\frac{4\pi G\rho(\lambda, \varphi, \Delta r)\Delta r^2}{Y}$$

$$\zeta_{\text{res}}(r, \lambda, \varphi) = G\rho(\lambda, \varphi, \Delta r)\Delta\lambda\Delta\varphi\Delta r [K_{1100} + O(\Delta^3)]$$

Tsoulis (2012) polyhedra algorithm + detection of special cases (Yang, Hirt and Pail, 2020)

Yang, Hirt, Pail (2020)

Point-masses with Tesseroid formulation

$$\zeta_{\text{res}}(2015_{\text{EIM2}}) = -4.54823 \text{ m}, \zeta_{\text{res}}(2015_{\text{EIM1}}) = -5.3585 \text{ m}$$

Mean tide System

$$\Delta\zeta = (\zeta_{\text{CRUST2015}_{100}} + \zeta_{\text{RTM}}) - \zeta_{\text{GN/GPS}}$$

**Height anomaly discrepancies**

**Height anomaly Polyhedra + Point Masses discrepancies**

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